

TIPE FILTER FASA LINIER

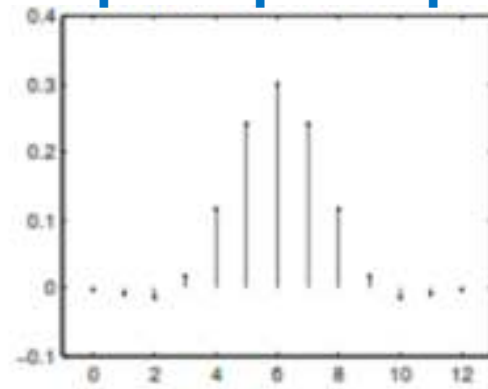
TIPE	RESPON IMPULS	
I	SIMETRI	GANJIL
II	SIMETRI	GENAP
III	ANTISIMETRI	GANJIL
IV	ANTISIMETRI	GENAP

Respon impulse untuk simetri dapat dituliskan:
 $h(n) = h(N-1-n)$

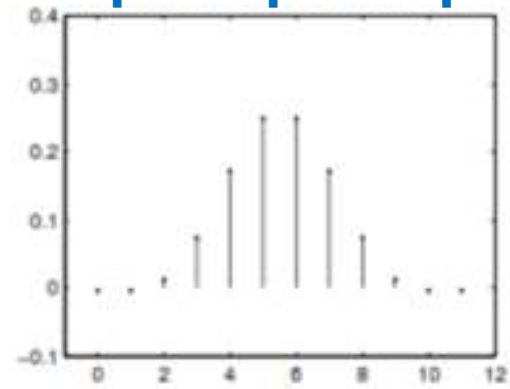
Sedangkan antisimetri:
 $h(n) = -h(N-1-n)$

Jika $h(n)$ bernilai kompleks, agar berfase linier maka $h(n)$ harus di conjugate-simmetry atau conjugate-anti-simmetry

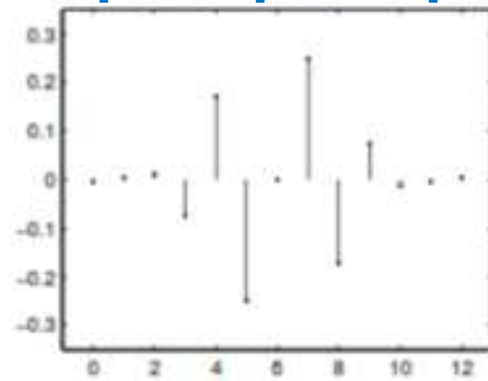
Respon impulse tipe 1



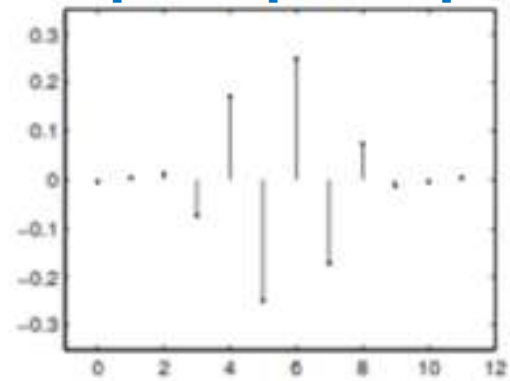
Respon impulse tipe 2



Respon impulse tipe 3



Respon impulse tipe 4





FIR fasa linier tipe 1 dengan panjang N=5:

Respon frekuensi:

$$\begin{aligned}H(e^{j\omega}) &= h_0 + h_1e^{-j\omega} + h_2e^{-2j\omega} + h_1e^{-3j\omega} + h_0e^{-4j\omega} \\&= e^{-2j\omega} (h_0e^{2j\omega} + h_1e^{j\omega} + h_2 + h_1e^{-j\omega} + h_0e^{-2j\omega}) \\&= e^{-2j\omega} (h_0(e^{2j\omega} + e^{-2j\omega}) + h_1(e^{j\omega} + e^{-j\omega}) + h_2) \\&= e^{-2j\omega} (2h_0 \cos(2\omega) + 2h_1 \cos(\omega) + h_2) \\&= A(\omega)e^{j\theta(\omega)}\end{aligned}$$

dimana:

$$\theta(\omega) = -2\omega$$

$$A(\omega) = 2h_0 \cos(2\omega) + 2h_1 \cos(\omega) + h_2 \quad \text{Nilai A ini real}$$



FIR fasa linier tipe 1 secara umum dengan panjang N:

Respon frekuensi:

$$H(e^{j\omega}) = A(\omega)e^{j\theta(\omega)}$$

Respon magnitude:

$$A(\omega) = h(M) + 2 \sum_{n=0}^{M-1} h(n) \cos((M-n)\omega)$$

Respon fasa:

$$\theta(\omega) = -M\omega$$

$$M = \frac{N-1}{2}$$



FIR fasa linier tipe 2 dengan panjang N=4:

Respon frekuensi:

$$\begin{aligned} H(e^{j\omega}) &= h_0 + h_1e^{-j\omega} + h_1e^{-2j\omega} + h_0e^{-3j\omega} \\ &= e^{-\frac{3}{2}j\omega} \left(h_0e^{\frac{3}{2}j\omega} + h_1e^{\frac{1}{2}j\omega} + h_1e^{-\frac{1}{2}j\omega} + h_0e^{-\frac{3}{2}j\omega} \right) \\ &= e^{-\frac{3}{2}j\omega} \left(h_0(e^{\frac{3}{2}j\omega} + e^{-\frac{3}{2}j\omega}) + h_1(e^{\frac{1}{2}j\omega} + e^{-\frac{1}{2}j\omega}) \right) \\ &= e^{-\frac{3}{2}j\omega} \left(2h_0 \cos\left(\frac{3}{2}\omega\right) + 2h_1 \cos\left(\frac{1}{2}\omega\right) \right) \\ &= A(\omega)e^{j\theta(\omega)} \end{aligned}$$

dimana:

$$\theta(\omega) = -\frac{3}{2}\omega$$

$$A(\omega) = 2h_0 \cos\left(\frac{3}{2}\omega\right) + 2h_1 \cos\left(\frac{1}{2}\omega\right)$$

Nilai A ini real



FIR fasa linier tipe 2 secara umum dengan panjang N:

Respon frekuensi: $H(e^{j\omega}) = A(\omega)e^{j\theta(\omega)}$

Respon magnitude: $A(\omega) = 2 \sum_{n=0}^{\frac{N}{2}-1} h(n) \cos((M-n)\omega)$

Respon fasa: $\theta(\omega) = -M\omega$

$$M = \frac{N-1}{2}$$

FIR fasa linier tipe 3 dengan panjang N=4:

Respon frekuensi:

$$\begin{aligned} H(e^{j\omega}) &= h_0 + h_1 e^{-j\omega} - h_1 e^{-3j\omega} - h_0 e^{-4j\omega} \\ &= e^{-2j\omega} (h_0 e^{2j\omega} + h_1 e^{j\omega} - h_1 e^{-j\omega} - h_0 e^{-2j\omega}) \\ &= e^{-2j\omega} (h_0 (e^{2j\omega} - e^{-2j\omega}) + h_1 (e^{j\omega} - e^{-j\omega})) \\ &= e^{-2j\omega} (2j h_0 \sin(2\omega) + 2j h_1 \sin(\omega)) \\ &= e^{-2j\omega} j (2h_0 \sin(2\omega) + 2h_1 \sin(\omega)) \\ &= e^{-2j\omega} e^{j\frac{\pi}{2}} (2h_0 \sin(2\omega) + 2h_1 \sin(\omega)) \\ &= A(\omega) e^{j\theta(\omega)} \end{aligned}$$

dimana:

$$\theta(\omega) = -2\omega + \frac{\pi}{2}$$

$$A(\omega) = 2h_0 \sin(2\omega) + 2h_1 \sin(\omega)$$

Nilai A ini real



FIR fasa linier tipe 3 secara umum dengan panjang N:

Respon frekuensi: $H(e^{j\omega}) = A(\omega)e^{j\theta(\omega)}$

Respon magnitude: $A(\omega) = 2 \sum_{n=0}^{M-1} h(n) \sin((M-n)\omega)$

Respon fasa: $\theta(\omega) = -M\omega + \frac{\pi}{2}$

$$M = \frac{N-1}{2}$$

FIR fasa linier tipe 4 dengan panjang N=5:

Respon frekuensi:

$$\begin{aligned} H(e^{j\omega}) &= h_0 + h_1e^{-j\omega} - h_1e^{-2j\omega} - h_0e^{-3j\omega} \\ &= e^{-\frac{3}{2}j\omega} \left(h_0e^{\frac{3}{2}j\omega} + h_1e^{\frac{1}{2}j\omega} - h_1e^{-\frac{1}{2}j\omega} - h_0e^{-\frac{3}{2}j\omega} \right) \\ &= e^{-\frac{3}{2}j\omega} \left(h_0(e^{\frac{3}{2}j\omega} - e^{-\frac{3}{2}j\omega}) + h_1(e^{\frac{1}{2}j\omega} - e^{-\frac{1}{2}j\omega}) \right) \\ &= e^{-\frac{3}{2}j\omega} \left(2jh_0 \sin\left(\frac{3}{2}\omega\right) + 2jh_1 \sin\left(\frac{1}{2}\omega\right) \right) \\ &= e^{-\frac{3}{2}j\omega} j \left(2h_0 \sin\left(\frac{3}{2}\omega\right) + 2h_1 \sin\left(\frac{1}{2}\omega\right) \right) \\ &= e^{-\frac{3}{2}j\omega} e^{j\frac{\pi}{2}} \left(2h_0 \sin\left(\frac{3}{2}\omega\right) + 2h_1 \sin\left(\frac{1}{2}\omega\right) \right) \\ &= A(\omega)e^{j\theta(\omega)} \end{aligned}$$

dimana:

$$\theta(\omega) = -\frac{3}{2}\omega + \frac{\pi}{2}$$

$$A(\omega) = 2h_0 \sin\left(\frac{3}{2}\omega\right) + 2h_1 \sin\left(\frac{1}{2}\omega\right) \quad \text{Nilai A ini real}$$



FIR fasa linier tipe 4 secara umum dengan panjang N:

Respon frekuensi:

$$H(e^{j\omega}) = A(\omega) e^{j\theta(\omega)}$$

Respon magnitude:

$$A(\omega) = 2 \sum_{n=0}^{\frac{N}{2}-1} h(n) \sin((M-n)\omega)$$

Respon fasa:

$$\theta(\omega) = -M\omega + \frac{\pi}{2}$$

$$M = \frac{N-1}{2}$$

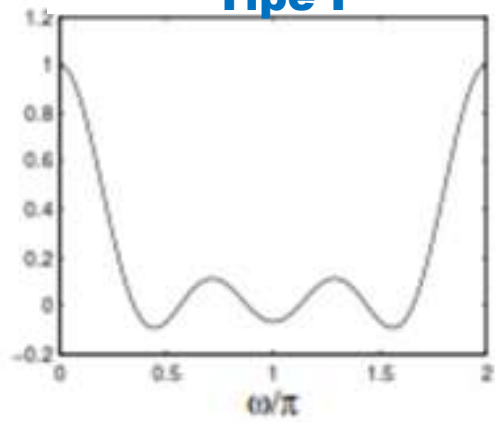
RINGKASAN RESPON MAGNITUDA, FASA UNTUK FIR FASA LINIER

Type	$\theta(\omega)$	$A(\omega)$
I	$-M\omega$	$h(M) + 2 \sum_{n=0}^{M-1} h(n) \cos((M-n)\omega)$
II	$-M\omega$	$2 \sum_{n=0}^{\frac{N}{2}-1} h(n) \cos((M-n)\omega)$
III	$-M\omega + \frac{\pi}{2}$	$2 \sum_{n=0}^{M-1} h(n) \sin((M-n)\omega)$
IV	$-M\omega + \frac{\pi}{2}$	$2 \sum_{n=0}^{\frac{N}{2}-1} h(n) \sin((M-n)\omega)$

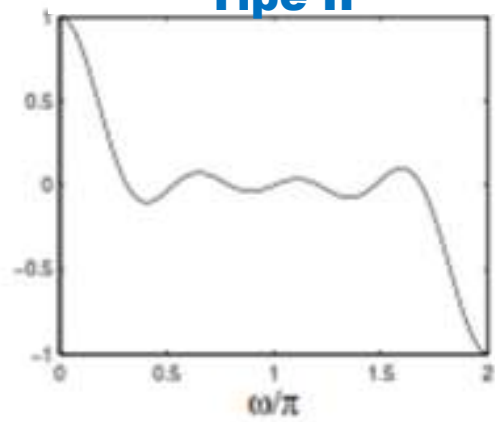
$$M = \frac{N-1}{2}$$

KARAKTERISTIK RESPON AMPLITUDA

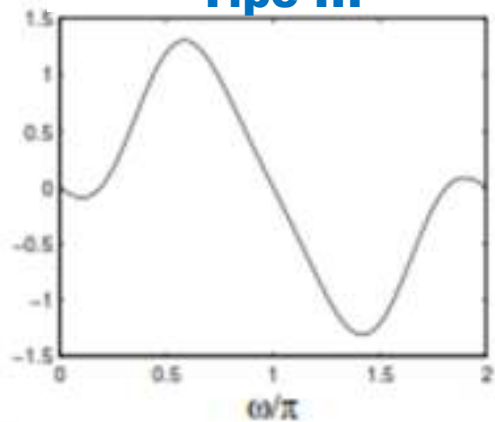
Respon Amplituda Tipe I



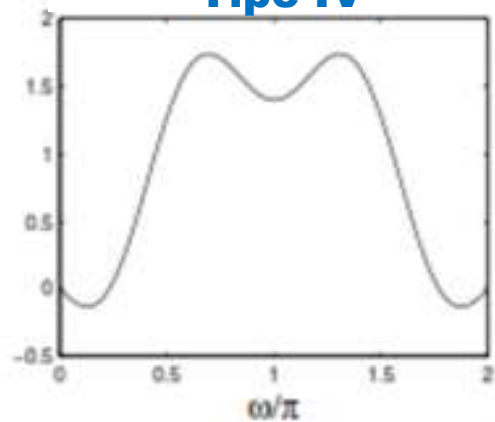
Respon Amplituda Tipe II



Respon Amplituda Tipe III



Respon Amplituda Tipe IV



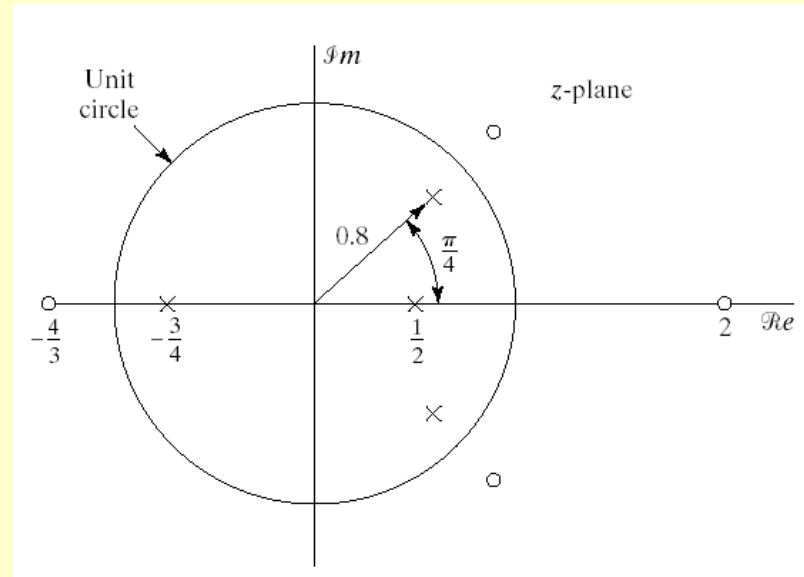
All-Pass System

- A system with frequency response magnitude constant
- Important uses such as compensating for phase distortion
- Simple all-pass system

$$H_{ap}(z) = \frac{z^{-1} - a^*}{1 - az^{-1}}$$

- Magnitude response constant

$$H_{ap}(e^{j\omega}) = \frac{e^{-j\omega} - a^*}{1 - ae^{-j\omega}} = e^{-j\omega} \frac{1 - a^* e^{j\omega}}{1 - ae^{-j\omega}}$$



- Most general form with real impulse response

$$H_{ap}(z) = A \prod_{k=1}^{M_r} \frac{z^{-1} - d_k}{1 - d_k z^{-1}} \prod_{k=1}^{M_c} \frac{(z^{-1} - c_k^*)(z^{-1} - c_k)}{(1 - c_k z^{-1})(1 - c_k^* z^{-1})}$$

- A: positive constant, d_k : real poles, c_k : complex poles

Phase of All-Pass Systems

$$H_{ap}(e^{j\omega}) = \frac{e^{-j\omega} - a^*}{1 - ae^{-j\omega}} = e^{-j\omega} \frac{1 - a^* e^{j\omega}}{1 - ae^{-j\omega}}$$

- Let's write the phase with a represented in polar form

$$\angle \left[\frac{e^{-j\omega} - re^{-j\theta}}{1 - re^{j\theta}e^{-j\omega}} \right] = -\omega - 2 \arctan \left[\frac{r \sin(\omega - \theta)}{1 - r \cos(\omega - \theta)} \right]$$

- The group delay of this system can be written as

$$\text{grd} \left[\frac{e^{-j\omega} - re^{-j\theta}}{1 - re^{j\theta}e^{-j\omega}} \right] = \frac{1 - r^2}{1 - 2r \cos(\omega - \theta) + r^2} = \frac{1 - r^2}{|1 - re^{j\theta}e^{-j\omega}|^2}$$

- For stable and causal system $|r| < 1$
 - Group delay of all-pass systems is always positive
- Phase between 0 and π is always negative

$$\arg[H_{ap}(e^{j\omega})] \leq 0 \quad \text{for} \quad 0 \leq \omega < \pi$$

Minimum-Phase System

- A system with all poles and zeros inside the unit circle
- Both the system function and the inverse is causal and stable
- Name “minimum-phase” comes from the property of the phase
 - Not obvious to see with the given definition
 - Will look into it
- Given a magnitude square system function that is minimum phase
 - The original system is uniquely determined
- Minimum-phase and All-pass decomposition
 - Any rational system function can be decomposed as

$$H(z) = H_{\min}(z)H_{\text{ap}}(z)$$

Example 1: Minimum-Phase System

- Consider the following system

$$H_1(z) = \frac{1 + 3z^{-1}}{1 + \frac{1}{2}z^{-1}}$$

- One pole inside the unit circle:
 - Make part of minimum-phase system
- One zero outside the unit circle:
 - Add an all-pass system to reflect this zero inside the unit circle

$$H_1(z) = \frac{1 + 3z^{-1}}{1 + \frac{1}{2}z^{-1}} = 3 \frac{1}{1 + \frac{1}{2}z^{-1}} \left(z^{-1} + \frac{1}{3} \right) = 3 \frac{1}{1 + \frac{1}{2}z^{-1}} \left(z^{-1} + \frac{1}{3} \right) \frac{1 - \frac{1}{3}z^{-1}}{1 - \frac{1}{3}z^{-1}}$$

$$H_1(z) = \left(3 \frac{1 - \frac{1}{3}z^{-1}}{1 + \frac{1}{2}z^{-1}} \right) \left(\frac{z^{-1} + \frac{1}{3}}{1 - \frac{1}{3}z^{-1}} \right) = H_{\min}(z)H_{\text{ap}}(z)$$

Example 2: Minimum-Phase System

- Consider the following system

$$H_2(z) = \frac{\left(1 + \frac{3}{2} e^{j\pi/4} z^{-1}\right) \left(1 + \frac{3}{2} e^{-j\pi/4} z^{-1}\right)}{1 - \frac{1}{3} z^{-1}}$$

- One pole inside the unit circle:
- Complex conjugate zero pair outside the unit circle

$$\begin{aligned} H_2(z) &= \frac{\left(1 + \frac{3}{2} e^{j\pi/4} z^{-1}\right) \left(1 + \frac{3}{2} e^{-j\pi/4} z^{-1}\right)}{1 - \frac{1}{3} z^{-1}} \\ &= \frac{\frac{3}{2} e^{j\pi/4} \frac{3}{2} e^{-j\pi/4} \left(\frac{2}{3} e^{-j\pi/4} + z^{-1}\right) \left(\frac{2}{3} e^{j\pi/4} + z^{-1}\right)}{1 - \frac{1}{3} z^{-1}} \end{aligned}$$

Example 2 Cont'd

$$H_2(z) = \frac{\frac{9}{4} \left(\frac{2}{3} e^{-j\pi/4} + z^{-1} \right) \left(\frac{2}{3} e^{j\pi/4} + z^{-1} \right)}{1 - \frac{1}{3} z^{-1}} \cdot \frac{\left(1 + \frac{2}{3} e^{-j\pi/4} z^{-1} \right) \left(1 + \frac{2}{3} e^{j\pi/4} z^{-1} \right)}{\left(1 + \frac{2}{3} e^{-j\pi/4} z^{-1} \right) \left(1 + \frac{2}{3} e^{j\pi/4} z^{-1} \right)}$$

$$H_2(z) = \frac{\frac{9}{4} \left(1 + \frac{2}{3} e^{-j\pi/4} z^{-1} \right) \left(1 + \frac{2}{3} e^{j\pi/4} z^{-1} \right)}{1 - \frac{1}{3} z^{-1}} \cdot \frac{\left(\frac{2}{3} e^{-j\pi/4} + z^{-1} \right) \left(\frac{2}{3} e^{j\pi/4} + z^{-1} \right)}{\left(1 + \frac{2}{3} e^{-j\pi/4} z^{-1} \right) \left(1 + \frac{2}{3} e^{j\pi/4} z^{-1} \right)}$$

$$H_2(z) = H_{\min}(z) H_{\text{ap}}(z)$$